

Figure 1

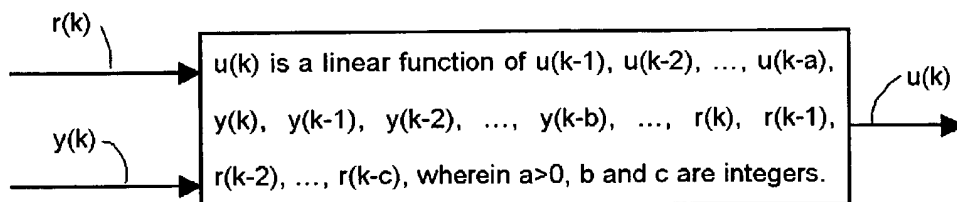


Figure 2: A PID controller or a linear controller